



VISOR® Product Overview

VISOR® vision sensors for factory automation

Next Generation

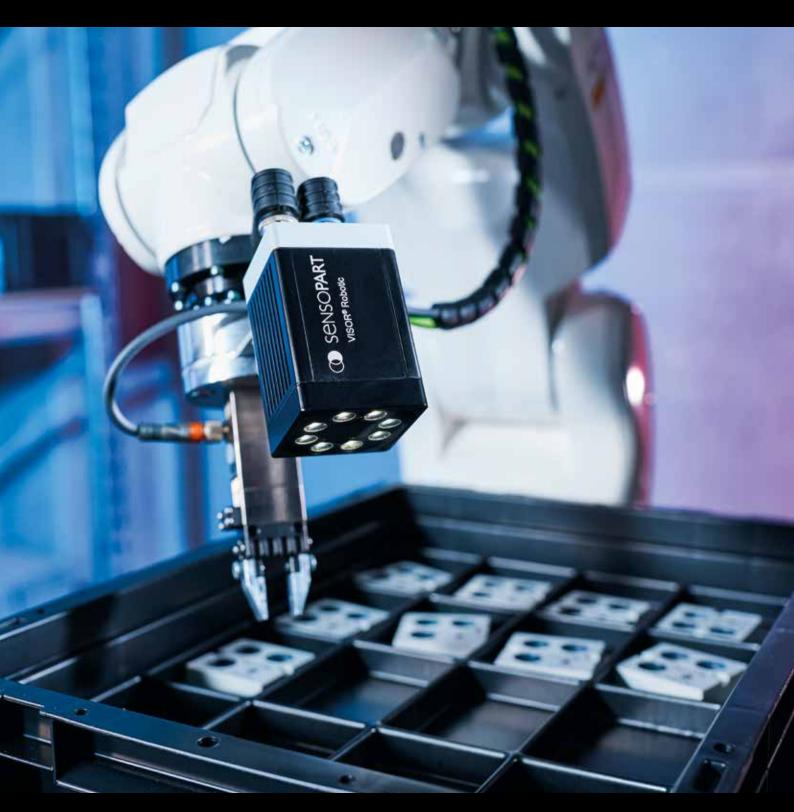






Calibration of vision sensors

Metric world and robot coordinates at a mouse click.



Increased efficiency when setting up vision sensors:

Vision sensor intelligence has risen continuously over recent years and can be trusted with more and more complex tasks. The calibration function offered by the VISOR® series is a prime example: it saves considerable time when setting up pick and place applications, as there is no need for programming in the robot control system or PLC. This represents a significant boost in efficiency both for users and integrators.



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Vision with foresight

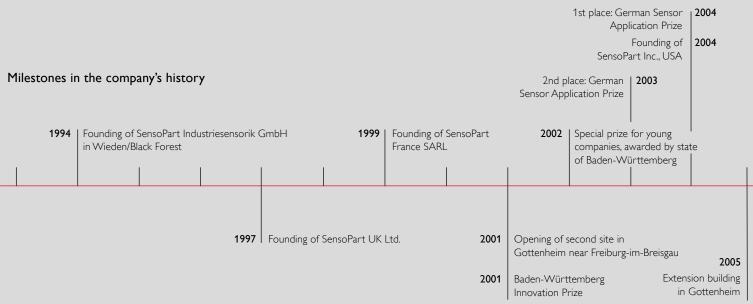


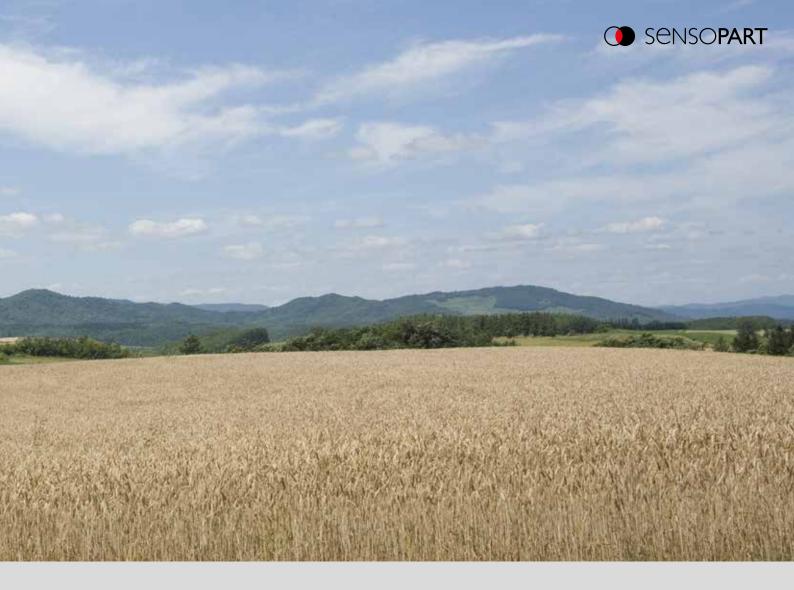
"Our standard is not what is possible today, but the vision of what will be achievable in future" - this has been our credo since the founding of SensoPart in 1994. Our aim is to remain one step ahead and to be able to offer our customers the most innovative products on the market.

When we have identified a path as correct we follow it consistently. As a family-run company we can act independently and as we see fit – a major prerequisite for the extremely successful

development that SensoPart has achieved since its start.

Successful products, now considered indispensable for modern factory automation, have been created from the many futureoriented ideas of earlier days. But we do not simply rest on our laurels - because we still have many ideas for the future. Here the future concepts of Industry 4.0 are playing an important role for us. Some of them have already been implemented with our products.







"Dependability, responsibility and trust"

SensoPart is a family-run German company and this also influences our attitude towards work: we believe that dependability is important, we take responsibility for our activities, and we value close and trusting relations within the company as well as with our customers and business partners.

/ h/am

Dr. Theodor Wanner,

Founder and Managing Director of SensoPart

| 2006 | Baden-Württemberg Innovation Prize | | | | | Auton | nation Award | 2014 | Vi | Innova | ems Design | 2017 |
|------|---------------------------------------|------|---------------------------|------|------|-----------------------------|--------------|------|----|------------|--------------------------|------|
| | | | | | | Auton | nation Award | 2014 | | (Sliver-Le | evel Award) | |
| | | | | | | 20 years | of SensoPart | 2014 | | | ening of the duction and | |
| | | 2009 | Freiburg Innovation Pr | rize | 2012 | Founding of SensoPart Ch | hina | | | | Gottenheim | |
| | | | | | | | | | | | | |

2008 ''Top 100" Innovation Prize

Thoroughly equipped

Sophisticated design and extensive features





- Integrated processing unit with high-performance signal processor
- Robust and vibration-resistant metal housing, IP 65 / IP 67
- Compact dimensions:
 71 x 45 x 45 mm





- Simple and flexible installation using dovetail mount
- Extensive range of mounting accessories and holders

Power supply and I/O, M12, 12-pin

- Power supply
- I/Os
- Encoder
- · External lighting

Configuration and data output, Ethernet, M12, 4-pin

- Ethernet
- EtherNet/IP
- PROFINET
- sFTP/SMB archiving
- SensoWeb

Unpack, **set up** – it's ready to run! Vision sensors have never been as easy and intuitive to use despite unprecedented levels of performance. The VISOR® is ready in just a few mouse clicks. Thanks to VISOR® technology from SensoPart, there is now a simple and effective solution for even the most challenging vision tasks. Whether these involve complex object shapes, color detection, data matrix codes, fluorescent display elements – our application-specific vision sensors reliably detect all relevant object characteristics.

Setup requires just a few simple steps

Complex tasks made easy - with VISOR® software packages

SensoFind

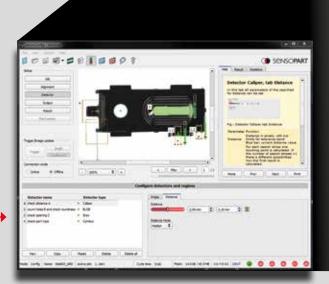
Lists all the VISOR® vision sensors available in the network. Configuration or Viewer mode can be accessed directly from here and offline simulation can also be started.



SensoConfig

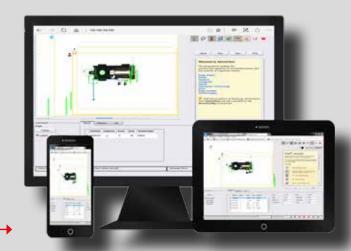
VISOR® configuration software.

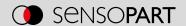
Complex inspection tasks can be easily set up in a step by step process. The effect of each setting is immediately visible on the screen. Comprehensive logic functions enable the direct assignment of complex inspection results to one of six digital result outputs. The integrated image recorder, which enables error analysis and simulations, is also very useful.

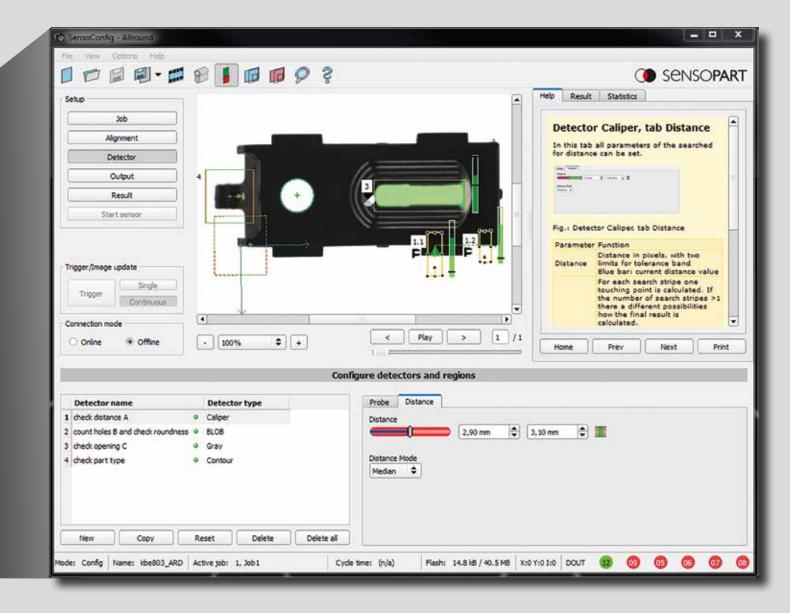


SensoView & SensoWeb

Once configuration has been completed, the vision sensor operates as a free-standing unit- i.e. without a PC connection. Data can of course be called up at any time while the sensor is running: a unique viewer software 'SensoView' with restricted user rights is available for this purpose — inadvertent changes to configuration settings are thus reliably avoided. 'SensoWeb'' enables easy connection to system visualisation by web browser. Professional image processing is that simple!







Step by step guide

- 1. Set up job and image
- 2. Set up image tracking and detectors
- 3. Result output/communication

A convincing portfolio

An impressive range of outstanding sensors

Advantages of VISOR® vision sensors

- Universal interface for all VISOR® devices, which means universal PLC modules
- Versions with increased depth of field, motorised focus adjustment
- PROFINET (Conformance Class B) with update rate of 4 ms, incl. image transmission via Ethernet
- Easily configurable image processing tools and preprocessing filters for reliable evaluation
- Image resolution can be scaled in software for high-speed analysis
- Standardised electrical and mechanical design
- ONE VISOR® software for ALL versions this minimises the need for training

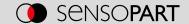


VISOR® red VISOR® white VISOR® infrared



VISOR® C-mount

Easily extendible

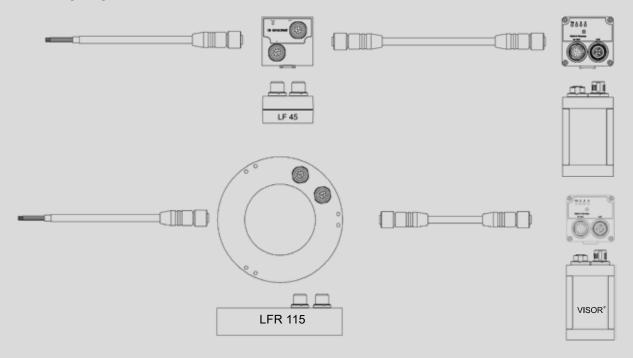


Innovative and user-friendly accessory and mounting concept



The MG 3A mounting bracket can be combined with mechanical accessories and external lighting.

External lighting can be controlled via VISOR®.



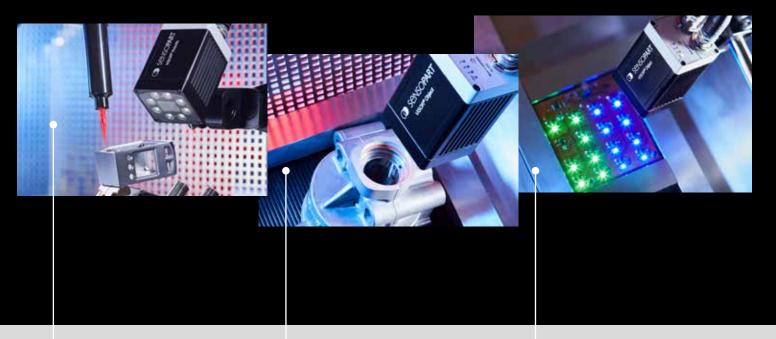
External lighting (panel light LF 45, ring light LFR 115) can be connected directly between the vision sensor and power supply.

VISOR® vision sensors

Image processing can be so easy.

VISOR® Allround

VISOR® Object



VISOR® Allround Object detection and identification in one device

- All evaluations ("Detectors") of VISOR® Object and VISOR® Code Reader united in one device
- Highly accurate evaluation via 1.5 megapixel chip
- Powerful color detection of version with color chip
- Ethernet, Profinet and EtherNet/IP are available for data communication

VISOR® Object

Reliable detection and classification of objects

- Detectors for presence and completeness checks as well as for simple measurement tasks
- Precise determination of X/Y position, orientation and tracking
- High evaluation accuracy through
 1.5 megapixel chip
- Comprehensive logic functions for the digital switching outputs
- Flexible definition of output data (header, trailer, net data)
- Correction of warps and distortions, conversion into millimetres thanks to easy calibration

VISOR® Object Color

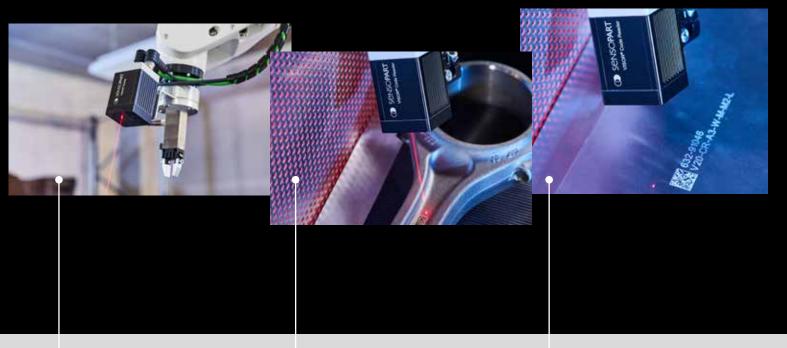
Improved object detection through supplementary color information

- Powerful color detection, even with small color nuances or fluorescent components
- Powerful part-finding and tracking
- High evaluation accuracy through
 1.5 megapixel color chip
- Up to 8 digital switching outputs



VISOR® Robotic

VISOR® Code Reader



VISOR® Robotic

The expert for robotics applications

- Different detectors for locating up to 10,000 components
- Check of space available around gripper
- Offset in VISOR® software for simple adjustment of gripper point
- Two calibration methods for robotics applications
- Offset of work plane through Z-offset function

VISOR® Code Reader standard Reading of barcodes and data matrix codes

- Flexible definition of output data (header, trailer, net data)
- String comparison with signalling via the digital switching output

VISOR® Code Reader Adv. / Prof.

Reading of barcodes and data matrix codes, as well as detection of optical characters (OCR)

- Reads bar codes as well as printed and directly marked data matrix codes reliably; can also read several codes simultaneously and combinations of 1D/2D codes
- Evaluation of quality parameters according to ISO/IEC 15415 and AIM DPM 2006
- Supplementary object detection for features outside the code with "Professional" version

Camera + software = vision!

With its portfolio of vision solutions, SensoPart covers the entire spectrum of industrial image processing. Our VISOR® vision sensors are based on a powerful smart camera in a compact sealed sensor housing with a standardised dovetail mount. They also feature integrated signal processing, LED lighting (white, red, infrared), data interfaces and digital I/Os, integrated lens or C-mount as well as user-friendly configuration software.

Product overview VISOR® vision sensors

| | VISOR® Allround Presence, completeness, measurement, color, reading of barcodes, 2D codes | | VISOR® Object | | | |
|---|--|--|---|---|--|--|
| | | | Presence, completeness, measuremen color | | | |
| | Advanced | Professional | Standard | Advanced | | |
| Resolution | | | | | | |
| V10 V10C 800 × 600 | Monochrome Color | - | | ome Color | | |
| Number of images per second V10 V10 C | 75 50 | - - | 75 | 5 50 | | |
| V20 V20C 1440 × 1080 | Monochro | me Color | - | Monochrome Colo | | |
| Number of images per second V20 V20 C | 40 | 20 | - - | 40 20 | | |
| Lighting | | white, r | red ¹ , infrared ¹ | | | |
| Multishot | , | / | | _ | | |
| Target laser | , | / | - | ✓ | | |
| Lenses | | | | | | |
| V10 wide medium narrow c-mount | ✓ ✓ | | √ √ √ − | √ √ √ √ | | |
| V20 wide medium narrow c-mount | ✓ ✓ | | - - - - | ∀ ∀ ∀ ∀ | | |
| nterfaces | | | | | | |
| Inputs outputs selectable | 2.1 | 2 6 | 2 2 4 | 2 2 6 | | |
| Encoder input | · | / | Z Z T | Z Z 0 ✓ | | |
| Ethernet EtherNet/IP Profinet SensoWeb | | / √ √ | | | | |
| | · · | | | · · | | |
| Service port | ` | | _ | ✓ | | |
| ob/Detectors | | | _ | | | |
| Number of jobs (max.) | | 55 | 8 | 255 | | |
| Number of detectors per job (max.) | 2. | 55 | 32 | 255 | | |
| Calibration | | | | | | |
| Calibration (scaling, perspective) | , | / | - | ✓ | | |
| Robot calibration | - | ✓ | | - | | |
| Preprocessing | | | | | | |
| Preprocessing filter | , | / | - | ✓ | | |
| Multiple image capture/Shutter variation | , | / | - | ✓ | | |
| Free-form search area | | / | | ✓ | | |
| Position tracking | | | | | | |
| Contour comparison (translation, rotation 360°) | , | / | | ✓ | | |
| Pattern matching (translation, rotation 360°) | | / | _ | ✓ | | |
| Edge detection (translation, rotation) | | / | _ | · · | | |
| | | | | | | |
| Object detection | | / | | | | |
| Contour comparison (translation, rotation 360°) | | | | √ | | |
| Multiple contour detection | • | / | - | ✓ | | |
| Pattern matching (translation, rotation 360°) | , | / | | ✓ | | |
| Grey level Contrast Brightness | , | / | | ✓ | | |
| Calliper | • | ✓ | | ✓ | | |
| BLOB | , | / | - | ✓ | | |
| dentification | | | | | | |
| Datacode | | _ | | _ | | |
| Datacode advanced | | / | | _ | | |
| Barcode | | _ | | _ | | |
| Barcode advanced | , | / | | _ | | |
| Clear text (OCR) | | / | | _ | | |
| Robotics functions | | | | | | |
| Result offset | _ | ✓ | | | | |
| Checking space around gripper | | √ | | | | |
| | | | | | | |
| Color detectors ² | | (| | 1 | | |
| Color field | | / | | √ | | |
| Color value | | <i>(</i> | - | √ | | |
| Color list | | / | - | ✓ | | |
| Color distance Binarisation | , | / | _ | ✓ | | |





VISOR® Robotic VISOR® Code Reader

Robotics, presence, completeness, measurement, positioning

Reading of barcodes, 2D codes, text

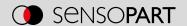
| | measurement, positioning | | text | | | |
|---|--------------------------|--------------------------------|------------------------------------|---|-----------------------|--|
| | Advanced | Professional | Standard | Advanced | Professional | |
| Resolution | | | | | | |
| V10 V10C 800 × 600 | Monochrome | - | | Monochrome | | |
| Number of images per second V10 V10 C | 75 | - - | | 75 - | | |
| V20 V20C 1440 × 1080 | Monochro | ome Color | - | Mono | chrome | |
| Number of images per second V20 V20 C | 40 | 20 | - - | 40 |) - | |
| Lighting | | whit | e, red¹, infrared¹ | | | |
| Multishot | | _ | | - | | |
| Target laser | | ✓ | - | | ✓ | |
| Lenses | | | | | | |
| V10 wide medium narrow c-mount | ✓ v | ∀ ∀ ∀ | √ √ √ − | √ √ | [v v | |
| V20 wide medium narrow c-mount | ✓ v | ∀ ∀ ∀ | - - - - | √ √ | 1 ✓ 1 ✓ | |
| Interfaces | | | | | | |
| Inputs outputs selectable | 2 | 2 6 | 2 2 4 | 2 | 2 6 | |
| Encoder input | | ✓ | | | ✓ | |
| Ethernet EtherNet/IP Profinet SensoWeb | ✓ v | ∕ √ √ | | ∀ ∀ ∀ ∀ | | |
| Service port | · | ✓ | - | | ✓ | |
| Job/Detectors | | | | | | |
| Number of jobs (max.) | 2 | 255 | 8 | 2 | 255 | |
| Number of detectors per job (max.) | 2 | 255 | 2 | 2 | 255 | |
| Calibration | | | | | | |
| Calibration (scaling, perspective) | | ✓ | | _ | | |
| Robot calibration | | ✓ | | _ | | |
| Preprocessing | | | | | | |
| Preprocessing filter | | ✓ | - | - | ✓ | |
| Multiple image capture/Shutter variation | | ✓ | - | - | ✓ | |
| Free-form search area | | ✓ | - | - | ✓ | |
| Position tracking | | | | | | |
| Contour comparison (translation, rotation 360°) | | ✓ | | _ | ✓ | |
| Pattern matching (translation, rotation 360°) | | ✓ | | _ | ✓ | |
| Edge detection (translation, rotation) | | ✓ | | _ | ✓ | |
| Object detection | | | | | | |
| Contour comparison (translation, rotation 360°) | | ✓ | | - | | |
| Multiple contour detection | | ✓ | | - | | |
| Pattern matching (translation, rotation 360°) | | ✓ | - | | ✓ | |
| Grey level Contrast Brightness | | ✓ | - | | ✓ | |
| Calliper | | ✓ | | - | | |
| BLOB | | ✓ | | - | | |
| Identification | | | | | | |
| Datacode | | _ | ✓ | | _ | |
| Datacode advanced | - | ✓ | - | | ✓ | |
| Barcode | - | - | ✓ | | _ | |
| Barcode advanced | - | ✓ | - | | ✓ | |
| Clear text (OCR) | - | ✓ | | - | ✓ | |
| Robotics functions | | | | | | |
| Result offset | | ✓ | | - | | |
| Checking space around gripper | | ✓ | | - | | |
| Color detectors ² | | | | | | |
| Color field | | - | | - | | |
| Color value | - | - | | - | | |
| Color list | - | - | | - | | |
| Color distance Binarisation | ✓ | ✓ | | - | | |

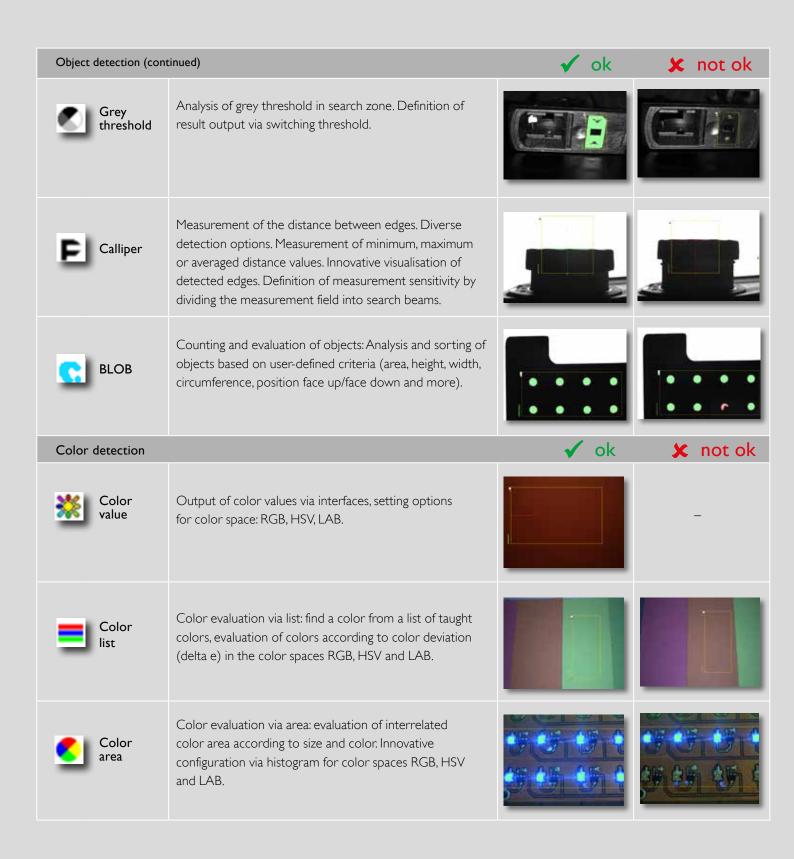
¹ not with color hardware V10C/V20C

VISOR® vision sensor

Detectors and application examples

| Identification | | | |
|------------------|---|---|----------|
| Barcode | Reading and quality assessment of most barcode types, such as EAN, UPC, RSS, 2/5 Interleaved, 2/5 Industrial, Code 32, Code 39, Code 93, Code 128, GS1, Pharmacode, Codabar. | Azzneimittel für Kinder unzuganglich Verschreibungspflichtig. • ZulNr.: PZN-6881219 | - |
| Data code | Reading and quality assessment of 2D codes, such as ECC200, QR code, ECC200 (GS1), QR code (GS1), PDF 417. High-performance decoder algorithm for directly marked, low-contrast and damaged codes. | | - |
| A OCR | Optical character reading of printed, laser-etched or dot- peened characters. High reading rate with difficult charac- ters or fluctuating marking quality through use of neural networks. Easy to use. Fast segmentation mode for high reading rates. | PZN -6182219 | - |
| Object detection | | √ ok | 🗴 not ok |
| Pattern matching | Object search based on pattern matching: once a pattern has been taught, consecutive images are then scanned for the same pattern. The degree of similarity can be defined by switching thresholds. Free form function for teaching random shapes with random orientation. | | -Cup |
| Contour | Object search based on contour comparison: once a contour has been taught, images are then scanned for the same contour. The degree of similarity can be defined by switching thresholds. Function for teaching random shapes. Orientation and scaling variations are configurable. | | |
| Contrast | Contrast analysis in search zone. Definition of result output via switching threshold. | CB SCNSOPART IN 115 MC4-21.12 1 EN + LB SHV DE SCHE STATISTICS 3 BU JOHN SARTHER ZONE 9 RG TRANS | |
| Brightness | Brightness analysis in search zone. Definition of result output via switching threshold. | | |





VISOR® vision sensor

Detectors and application examples

| Position tracking | | ✓ | ok | × | not ok |
|-----------------------|--|---------------------|-----------|---------|------------|
| /// Edge detection | High-performance edge finder for position tracking. Combination of different search strategies possible. Innovative visualisation of edges found. Definition of measurement sensitivity by dividing the measurement field into search beams. | 4 | 2 | | : : : : |
| Pattern matching | Object search based on pattern matching: once a pattern has been taught, consecutive images are then scanned for the same pattern. The degree of similarity can be defined by switching thresholds. Free form function for teaching random shapes. Detection of rotated patterns. | a-Cup | | -Cup | |
| Contour | Object search based on contour comparison: once a contour has been taught, images are scanned for the same contour. The degree of similarity can be defined by switching thresholds. Free form function for teaching random shapes. Orientation and scaling variations are configurable. | | | | 3 |
| Functions & preproc | essing filters | | | | |
| Pattern matching | Object search based on pattern matching: once a pattern hand for the same pattern. The degree of similarity can be defor teaching random shapes. | ~ | | ~ | |
| Filter | Large number of preprocessing filters to improve the pictur | re before actual in | nage proc | essing. | |
| Color filters | Definition of any color as software color filter to enable OC the highlighting of edges during object detection tasks (e.g. t | | | | |

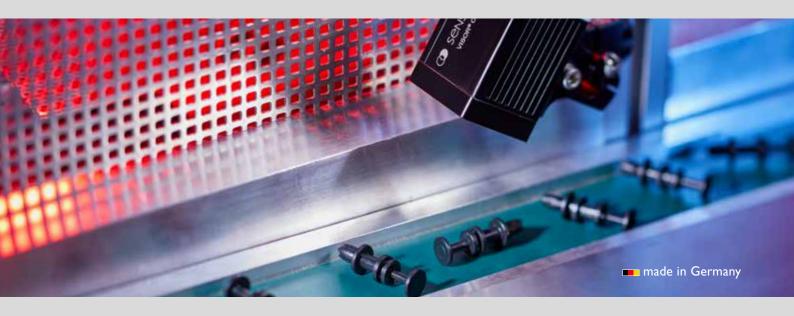
Interfaces and tools



| Interfaces | |
|--|--|
| SensoWeb | Visualisation of images and results. Easy connection to system visualisation by web browser. |
| PROFI [®] | Industrial Ethernet in compliance with PROFINET standard (Conformance Class B) through integrated Ethernet interface.VISOR® control options via PROFINET commands. |
| EtherNet/IP EtherNet/IP | Industrial Ethernet in compliance with EtherNet/IP standard through integrated Ethernet interface.VISOR® control options via EtherNet/IP commands. |
| Ethernet TCP/IP | Ethernet interface with user-configurable protocol.VISOR® control options via TCP/IP commands. |
| Calibration | |
| Calibration (scaling/ perspective) | Output of results in customised units (mm, cm, inch). Effects of perspective corrected according to the calibration method. |
| Robotic calibration | Output of results in customised units (mm, cm, m, inch) in a world coordinates system. A number of different methods are available for high flexibility. |

VISOR® Allround

Advanced allround vision sensor for complex inspection tasks.

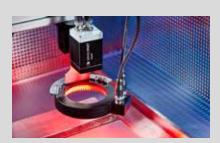




VISOR® Allround — Object detection in color plus identification united in one device. The VISOR® Allround is a real multi-talent among vision sensors. In the allround version, the device combines the functions of the object sensor (i.a. calibration, pattern matching, contour, calliper, BLOB) with the powerful tools of the code reader (barcode, datamatrix and optical character recognition).

HIGHLIGHTS OF VISOR® ALLROUND

- All evaluations ("Detectors") of object sensor and code reader combined in one device
- Precise determination of X/Y position, orientation and tracking
- Can be used for all common 2D-Codes (ECC 200-Datamatrix) and common 1D-barcodes
- User-friendly configuration and viewer software with graded user rights and online help



Raised or recessed object details — such as embossed digits and characters on a credit card — are difficult to detect with standard image processing methods. A remedy for this problem was found in the new Multishot function of VISOR® vision sensor range of SensoPart.



VISOR® Allround – Object detection plus identification.

The VISOR® Allround combines object detection functions with powerful code reading tools. When feeding parts in correct alignment or positioning components, additional data matrix codes for example can also be read. With a resolution of up to 1.5 megapixel even the smallest details are reliably detected and evaluated.

In addition to the monochrome version, the VISOR® Allround is also available as a color version with up to 1.5 megapixel.

Thus additional "Detectors" are available for color evaluation. Even the subtlest nuances in shade can be reliably detected. The relevant object colors, for example, can be taught-in quite simply at the push of a button or - thanks to the intuitive color histogram - set graphically for each channel in the color space. The authorised color tolerances can be defined by the user:

| VISOR® Allround – product overview | | | | | |
|------------------------------------|------------------|------------------------|---------------|-------------------------------|--|
| | Product variants | Resolution | Field of view | Integrated lighting | |
| V20x-ALL-A3-xxx | Advanced | 1440 × 1080 mono/color | wide | White, red* or infrared* LEDs | |
| V20x-ALL-A3-xxx | Advanced | 1440 × 1080 mono/color | medium | White, red* or infrared* LEDs | |
| V20x-ALL-A3-xxx | Advanced | 1440 × 1080 mono/color | narrow | White, red* or infrared* LEDs | |
| V20x-ALL-A3-C-2 | Advanced | 1440 × 1080 mono/color | C-mount | None | |
| V20x-ALL-P3-xxx | Professional | 1440 × 1080 mono/color | wide | White, red* or infrared* LEDs | |
| V20x-ALL-P3-xxx | Professional | 1440 × 1080 mono/color | medium | White, red* or infrared* LEDs | |
| V20x-ALL-P3-xxx | Professional | 1440 × 1080 mono/color | narrow | White, red* or infrared* LEDs | |
| V20x-ALL-P3-C-2 | Professional | 1440 x 1080 mono/color | C-mount | None | |
| V10x-ALL-A3-xxx | Advanced | 800 × 600 mono/color | wide | White, red* or infrared* LEDs | |
| V10x-ALL-A3-xxx | Advanced | 800 × 600 mono/color | medium | White, red* or infrared* LEDs | |
| V10x-ALL-A3-xxx | Advanced | 800 × 600 mono/color | narrow | White, red* or infrared* LEDs | |
| V10x-ALL-A3-C-2 | Advanced | 800 x 600 mono/color | C-mount | None | |

^{*}only with monochrome version

VISOR® Allround

System description

VISOR® Allround – Object detection in color plus identification combined in one device

The VISOR® Allround leaves nothing to be desired. The VISOR® Allround combines the functions of the object sensor (i.a. calibration, pattern matching, contour, calliper, BLOB) with the powerful tools of the code reader (barcode, datamatrix and optical character recognition). When feeding parts in correct alignment or positioning components, additional data matrix codes for example can now also be read. With a resolution of up to 1.5 megapixel even the smallest details are reliably detected and evaluated.

Special image filters for image pre-processing can be used, e.g. to highlight edges or to suppress distracting details.

Communication interfaces

In addition to EtherNet/IP and TCP/IP, the VISOR® vision sensors also support the fieldbus standard Profinet IO and thus "understand" the most common communication standards of Industrial Ethernet. Thanks to freely available PLC function blocks for Siemens S7, Codesys and Allen Bradley, the VISOR® can also be easily and flexibly connected to PLC environments. The new VISOR® Allround is thus one of the most powerful vision sensors in the market.

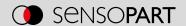
Raised or recessed object details – such as embossed digits and characters on a credit card – are difficult to detect with standard image processing methods. Even use of lateral lighting generally results in poorly identifiable contours due to overexposure and shadows. The solution comes in the shape of SensoPart's VISOR® vision sensor series with the new Multishot function. Contours now stand out clearly so that raised or recessed letters and digits can be easily read, e.g. using the vision sensor's OCR function. Other application examples for VISOR® Multishot include the reading of data matrix codes moulded directly into plastic surfaces, detection of damage such as dents or scratches, or the recognition of raised adhesive beads on the same colored background.

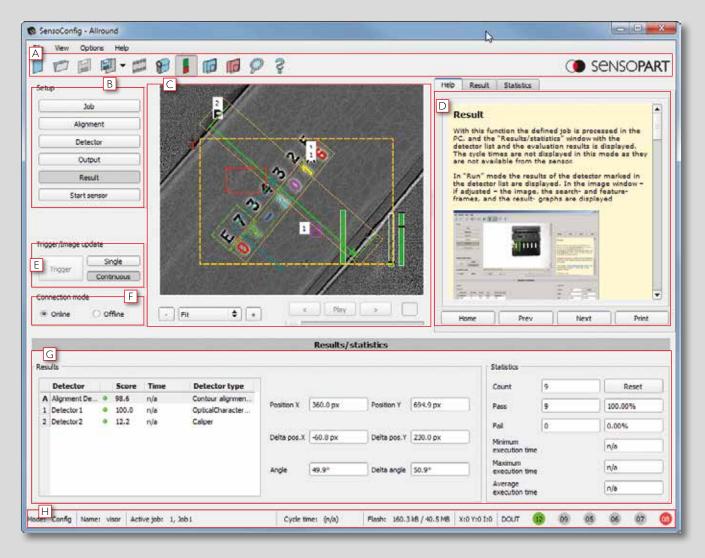
Product variants VISOR® Allround

| 110ddet variants visor 70 | VISOR® Allround | | | | |
|---|---------------------|---|--|--|--|
| | VI3OK~ | Aliround | | | |
| | ment, color, read | eteness, measure- ding of barcodes, codes | | | |
| | Advanced | Professional | | | |
| Resolution | | | | | |
| V10 V10C 800 × 600 | Monochrome, | _ | | | |
| Number of images per second V10 V10 C | Color 75 50 | -1- | | | |
| V20 V20C 1440 × 1080 | · | me Color | | | |
| Number of images per second V20 V20 C | | 20 | | | |
| Lighting | white, r | ed¹, infrared¹ | | | |
| Multishot | , | / | | | |
| Target laser | , | / | | | |
| Lenses | | | | | |
| V10 wide medium narrow c-mount | ✓ ✓ | | | | |
| V20 wide medium narrow c-mount | ✓ ✓ | | | | |
| Interfaces | | | | | |
| Inputs outputs selectable | 2 1 | 2 6 | | | |
| Encoder input | , | / | | | |
| Ethernet EtherNet/IP Profinet SensoWeb | ✓ ✓ | | | | |
| Service port | , | / | | | |
| Job/Detectors | | | | | |
| Number of jobs (max.) | 2. | 55 | | | |
| Number of detectors per job (max.) | 2. | 55 | | | |
| Calibration | | | | | |
| Calibration (scaling, perspective) | , | / | | | |
| Robot calibration | - | ✓ | | | |
| Preprocessing | | | | | |
| Preprocessing filter | | / | | | |
| Multiple image capture/Shutter variation | | / | | | |
| Free-form search area | , | / | | | |
| Position tracking Contour comparison (translation, rotation 360°) | , | / | | | |
| Pattern matching (translation, rotation 360°) | | / | | | |
| Edge detection (translation, rotation) | , | / | | | |
| Object detection | | | | | |
| Contour comparison (translation, rotation 360°) | , | / | | | |
| Multiple contour detection | , | / | | | |
| Pattern matching (translation, rotation 360°) | , | / | | | |
| Grey level Contrast Brightness | , | / | | | |
| Calliper | • | / | | | |
| BLOB | , | / | | | |
| Identification | | | | | |
| Datacode | | _ | | | |
| Datacode advanced | • | / | | | |
| Barcode | | - | | | |
| Barcode advanced | • | / | | | |
| Clear text (OCR) | | / | | | |
| Robotics functions | | | | | |
| Result offset | _ | · · | | | |
| Checking space around gripper | _ | · · | | | |
| Color detectors ² Color field | | / | | | |
| Color value | | / | | | |
| Color list | | , , | | | |
| Color distance Binarisation | | , / | | | |
| CO.OF GISTAIRCE DITIALISATION | | | | | |

¹ not with color hardware V10C/V20C

² only color hardware



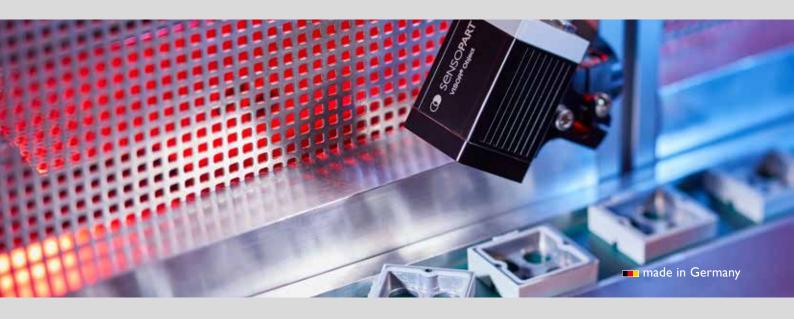


Overview of the user interface

- A Menu bar: rapid access to the most important functions.
- B Setup navigation: dependable user guidance through the configuration process.
- [C] Image window: live picture of the object with graphic display of inspection area and results.
- D Context help: precise information on every work step.
- Trigger function: triggered operation or free-running, single picture or serial switching.
- F Online/offline operation: operating with sensor connected or simulation with stored pictures.
- G Result window: Overview of all results.
- H Status line: current information on active job and on state of outputs.

VISOR® Object

Detects the right part in the wrong place and vice versa.





The one with a BLOB: With the BLOB detector (Binary Large Object), the VISOR® detects even small differences between objects, counts parts or detects whether a part is face up or face down.



The same or not the same?
The VISOR® detects even the smallest of color nuances more reliably than the human eye. This allows, for example, the detection of color deviations or the sorting of parts by color.

HIGHLIGHTS OF VISOR® OBJECT

- Detectors for presence and completeness checks as well as for simple measurement tasks
- Precise position determination: x/y-position and orientation
- Improved object detection through additional color information
- Comprehensive logic functions for the digital switching outputs
- Flexible definition of output data
- Support of EtherNet/IP and PROFINET
- Comprehensive for archiving images and data
- Correction of warps and distortions, conversion into millimetres thanks to easy calibration



Objects that sometimes appear in unexpected positions and have complex shapes and details – classic switching sensors would be completely overwhelmed by such detection tasks. Not the VISOR® Object from SensoPart: it always maintains its overview, detecting defective parts, parts in the wrong position, wrong orientation, wrong sequence or a combination of them all – in an instant. The comprehensive calibration functions range from a simple scaling factor to the correction of image and lens distortions at a mouse click. With its highly precise position and orientation detection, our VISOR® Object is one of the best in its class.

Seven detectors plus position detection

An expansive range of detectors is available for inspection tasks and evaluations: pattern matching, contour detection, calliper, BLOB, brightness, grey threshold and contrast detection. Position tracking offers reliable detection of those features that do not repeatedly appear in the original position taught. All evaluations take place relative to the current part position and orientation, without them having to be defined for every possible position of an individual feature. The color version features detectors for color detection, enabling VISOR® to also distinguish between the finest nuances in shade. This powerful tool allows you to solve even demanding applications confidently!

| VISOR® Object – product overview | | | | |
|----------------------------------|------------------|------------------------|---------------|-------------------------------|
| | Product variants | Resolution | Field of view | Integrated lighting |
| V20x-OB-A3-xxx | Advanced | 1440 x 1080 mono/color | wide | White, red* or infrared* LEDs |
| V20x-OB-A3-xxx | Advanced | 1440 x 1080 mono/color | medium | White, red* or infrared* LEDs |
| V20x-OB-A3-xxx | Advanced | 1440 x 1080 mono/color | narrow | White, red* or infrared* LEDs |
| V20x-OB-A3-C-2 | Advanced | 1440 x 1080 mono/color | C-mount | None |
| V10x-OB-S3-xxx | Standard | 800 x 600 mono/color | wide | White, red* or infrared* LEDs |
| V10x-OB-S3-xxx | Standard | 800 x 600 mono/color | medium | White, red* or infrared* LEDs |
| V10x-OB-S3-xxx | Standard | 800 x 600 mono/color | narrow | White, red* or infrared* LEDs |
| V10x-OB-A3-xxx | Advanced | 800 x 600 mono/color | wide | White, red* or infrared* LEDs |
| V10x-OB-A3-xxx | Advanced | 800 x 600 mono/color | medium | White, red* or infrared* LEDs |
| V10x-OB-A3-xxx | Advanced | 800 x 600 mono/color | narrow | White, red* or infrared* LEDs |
| V10x-OB-A3-C-2 | Advanced | 800 × 600 mono/color | C-mount | None |

^{*}only with monochrome version

VISOR® Object

System description

The VISOR® Object from SensoPart not only impresses with its excellent performance data, but also with its sophisticated operating concept: even the definition of complex inspection tasks is achieved rapidly and without complication thanks to its comfortable and easily understood user interface — even without detailed image-processing knowledge. You define and test your inspection tasks ("job") and desired evaluations ("detectors") in a few intuitive setup steps.

The effect of every setting is immediately visible in the image. Comprehensive logic functions allow the direct assignment of more complex inspection results to one of six digital result outputs. Time-based control of signal output is also possible via the integrated encoder function. The integrated image recorder, with which you can carry out fault analyses and simulations, is also very helpful.

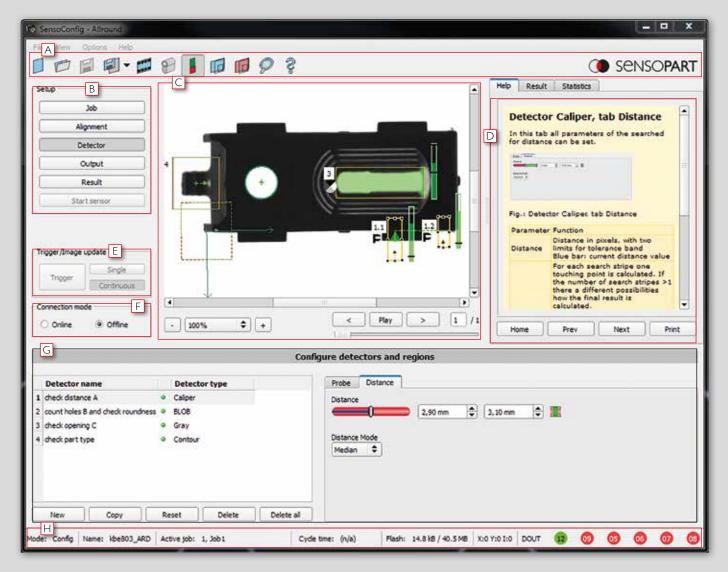
Everything in view with the Viewer: after completing configuration, the vision sensor works in your production plant autonomously, i.e. without a PC connection. Of course, data can be called up at any time during running operation: our own Viewer software "SensoView" with hierarchical user rights (reliably preventing unintentional changes to the configuration) is available for this. "SensoWeb" enables a simple integration into the plant visualisation via web browser. Professional image processing can be this simple and comfortable!

Product variants VISOR® Object

| Product variants VISOR® C | bject | | |
|---|------------------------------------|---|--|
| | VISOR® | Object | |
| | Presence, co measurem | • | |
| | Standard | Advanced | |
| Resolution | | | |
| V10 V10C 800 × 600 | Monochro | me Color | |
| Number of images per second V10 V10 C | 75 | 50 | |
| V20 V20C 1440 × 1080 | - | Monochrome Color | |
| Number of images per second V20 V20 C | - - | 40 20 | |
| Lighting | white, re | ed¹, infrared¹ | |
| Multishot | - | - | |
| Target laser | - | ✓ | |
| Lenses | | | |
| V10 wide medium narrow c-mount | √ √ √ − | | |
| V20 wide medium narrow c-mount | - - - - | ∀ ∀ ∀ ∀ | |
| Interfaces | | | |
| Inputs outputs selectable | 2 2 4 | 2 2 6 | |
| Encoder input | - | ✓ | |
| Ethernet EtherNet/IP Profinet SensoWeb | ✓ ✓ | √ √ | |
| Service port | - | ✓ | |
| Job/Detectors | | | |
| Number of jobs (max.) | 8 | 255 | |
| Number of detectors per job (max.) | 32 | 255 | |
| Calibration | | | |
| Calibration (scaling, perspective) | - | ✓ | |
| Robot calibration | - | - | |
| Preprocessing | | | |
| Preprocessing filter | - | ✓ | |
| Multiple image capture/Shutter variation | - | ✓ | |
| Free-form search area | v | (| |
| Position tracking | | | |
| Contour comparison (translation, rotation 360°) | ٧ | / | |
| Pattern matching (translation, rotation 360°) | _ | ✓ | |
| Edge detection (translation, rotation) | _ | ✓ | |
| Object detection | | | |
| Contour comparison (translation, rotation 360°) | | / | |
| Multiple contour detection | _ | ✓ | |
| Pattern matching (translation, rotation 360°) | | / | |
| Grey level Contrast Brightness | | / | |
| Calliper | _ | ✓ | |
| BLOB | _ | ✓ | |
| Identification | | | |
| Datacode | _ | - | |
| Datacode advanced | _ | - | |
| Barcode | _ | - | |
| Barcode advanced | _ | | |
| Clear text (OCR) | _ | | |
| Robotics functions | | | |
| Result offset | - | - | |
| Checking space around gripper | - | - | |
| Color detectors ² | | | |
| Color field | ٧ | / | |
| Color value | - | ✓ | |
| Color list | _ | ✓ | |
| | | √ | |
| Color distance Binarisation | _ | Y | |

¹ not with color hardware V10C/V20C





Overview of the user interface

- A Menu bar: rapid access to the most important functions.
- B Setup navigation: dependable user guidance through the configuration process.
- [C] Image window: live picture of the object with graphic display of inspection area and results.
- D Context help: precise information on every work step.
- Trigger function: triggered operation or free-running, single picture or serial switching.
- **Online/offline operation:** operating with sensor connected or simulation with stored pictures.
- G Configuration window: input of parameters for every navigation step.
- H Status line: current information on active job and on state of outputs.

VISOR® Robotic

An eye on everything – the vision sensor for robotics applications





The VISOR® Robotic detects the component's position in a universal tray. It can then be reliably removed. Up to 255 configurations enable utmost production flexibility.



The VISOR® Robotic determines the exact position of the sensor housing. Offset data is used to correct the robot's trajectory.

HIGHLIGHTS OF VISOR® ROBOTIC

- User-friendly configuration and display software
- Different detectors for locating up to 10,000 components
- Gripping space check check for available space around gripper
- Result offset correction in VISOR® software for simple adjustment of gripper point
- Two calibration methods for robotics applications:
 - Calibration plate: simple, fast and precise
 - Point pair list: considerable flexibility when selecting calibration object and field of view
- Offset of work plane through Z-offset function
- Integrated and standardised interfaces (PROFINET, EtherNet/IP,TCP/IP)
- Flexible output protocol
- The right version for every application
 - Different resolutions
 - Focal length of 6 mm to 75 mm
 - Monochrome and color version



Picking up components

Feeding systems in a production line are becoming increasingly versatile – in addition to universal trays, components can be supplied with utmost flexibility using hopper feeders. Thanks to the VISOR® Robotic, components can be reliably located and gripped with both feed options. When loose components are supplied, the sensor not only checks their position but also inspects the free space around the gripper. The VISOR® determines both sets of information and sends them to the robot controller via one of the integrated and standardised process interfaces. The process is managed on the basis of this information – the object is gripped or the feeder is triggered.

The application can also be flexibly adapted to individual goods carriers without the need for a costly centring device. The VISOR® detects the position and the fill level of the tray and transmits this information to the robot. If the camera is mounted in a stationary manner, this is cycle time-neutral.

Placing parts

What happens after components have been reliably collected by the gripper? The VISOR® Robotic also supplies important information for the next work steps, and demonstrates its skills in robot-controlled applications, such as the placing of screws, the mounting of clips or the application of glue. The detection of component positions is carried out effortlessly; this allows the correction of any offset and increases the quality of production. Knowledge of the exact position of a component ensures, for example, the precise insertion of a windscreen. Mechanical effort is reduced, and the production line becomes even more flexible. The VISOR® Robotic concept enables direct communication between the VISOR® and the robot, an additional instance is no longer necessary for many applications.

| VISOR® Robotic – product overview | | | | | |
|-----------------------------------|------------------|------------------------|---------------|-------------------------------|--|
| | Product variants | Resolution | Field of view | Integrated lighting | |
| V20x-RO-A3-xxx | Advanced | 1440 x 1080 mono/color | wide | White, red* or infrared* LEDs | |
| V20x-RO-A3-xxx | Advanced | 1440 x 1080 mono/color | medium | White, red* or infrared* LEDs | |
| V20x-RO-A3-xxx | Advanced | 1440 x 1080 mono/color | narrow | White, red* or infrared* LEDs | |
| V20x-RO-A3-C-2 | Advanced | 1440 x 1080 mono/color | C-mount | None | |
| V20x-RO-P3-xxx | Professional | 1440 x 1080 mono/color | wide | White, red* or infrared* LEDs | |
| V20x-RO-P3-xxx | Professional | 1440 x 1080 mono/color | medium | White, red* or infrared* LEDs | |
| V20x-RO-P3-xxx | Professional | 1440 x 1080 mono/color | narrow | White, red* or infrared* LEDs | |
| V20x-RO-P3-C-2 | Professional | 1440 x 1080 mono/color | C-mount | None | |
| V10-RO-A3-xxx | Advanced | 800 x 600 mono | wide | White, red or infrared LEDs | |
| V10-RO-A3-xxx | Advanced | 800 × 600 mono | medium | White, red or infrared LEDs | |
| V10-RO-A3-xxx | Advanced | 800 x 600 mono | narrow | White, red or infrared LEDs | |
| V10-RO-A3-C-2 | Advanced | 800 x 600 mono | C-mount | None | |

^{*}only with monochrome version

VISOR® Robotic

System description

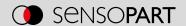
A diverse specialist

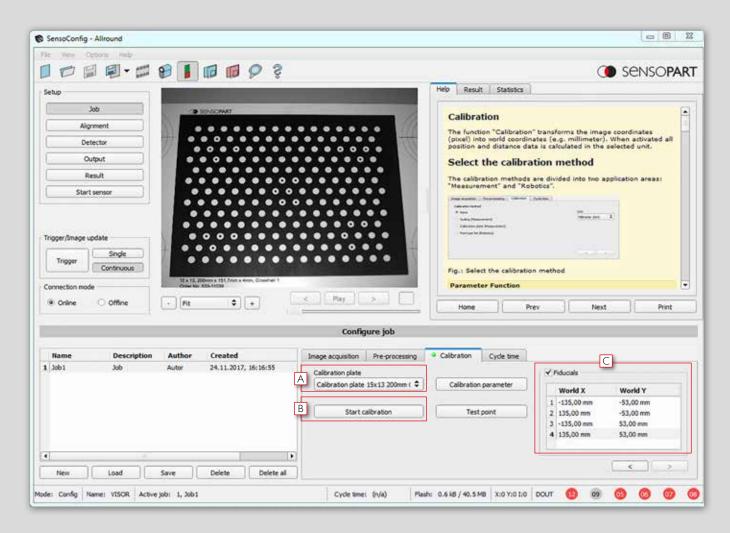
Expectations of today's robotics solutions are steadily rising in the context of Industry 4.0, paired with a simultaneous desire for greater ease-of-use. And this is precisely where the VISOR® Robotic demonstrates its outstanding ability. Available in several versions, it offers the perfect solution for a variety of automation tasks. Designed with integrated and standardised interfaces, VISOR® Robotic can be easily incorporated in existing installations and systems, and thanks to different calibration methods and flexible data structures, it is also suited to a diverse range of procedures.

Product variants VISOR® Robotic

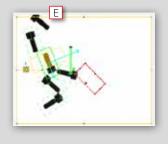
| | VISOR® Robotic | |
|---|--|--|
| | Robotics, presence, completeness, measurement, positioning | |
| | Advanced | Professional |
| Resolution | | |
| V10 V10C 800 × 600 | Monochrome | - |
| Number of images per second V10 V10 C | 75 | - - |
| V20 V20C 1440 × 1080 | Monochro | me Color |
| Number of images per second V20 V20 C | | 20 |
| Lighting | white, r | red ¹ , infrared ¹ |
| Multishot | | - |
| Target laser | • | ✓ |
| Lenses | | |
| V10 wide medium narrow c-mount | | [√ √ |
| V20 wide medium narrow c-mount | ✓ ✓ | |
| Interfaces | | |
| Inputs outputs selectable | 2 | 2 6 |
| Encoder input | | ✓ |
| Ethernet EtherNet/IP Profinet SensoWeb | ✓ ✓ | [√ √ |
| Service port | | ✓ |
| Job/Detectors | | |
| Number of jobs (max.) | 2 | 55 |
| Number of detectors per job (max.) | 2 | 55 |
| Calibration | | |
| Calibration (scaling, perspective) | | ✓ |
| Robot calibration | , | ✓ |
| Preprocessing | | |
| Preprocessing filter | , | ✓ |
| Multiple image capture/Shutter variation | , | ✓ |
| Free-form search area | , | ✓ |
| Position tracking Contour comparison (translation, rotation | | √ |
| 360°) Pattern matching (translation, rotation 360°) | | ✓ |
| Edge detection (translation, rotation) | | ✓ |
| Object detection | | |
| Contour comparison (translation, rotation 360°) | | √ |
| | | , ✓ |
| Multiple contour detection | | |
| Pattern matching (translation, rotation 360°) | √ | |
| Grey level Contrast Brightness | √ | |
| Calliper | √ | |
| BLOB | • | V |
| Identification | | |
| Datacode | | _ |
| Datacode advanced | _ | ✓ |
| Barcode | _ | _ |
| Barcode advanced | - | √ |
| Clear text (OCR) | - | ✓ |
| Robotics functions | | , |
| Result offset | | ✓ ✓ |
| Checking space around gripper | | V |
| Color detectors ² | | |
| Color field | | - |
| Color value | - | - |
| Color list | - | - |
| Color distance Binarisation | ✓ | ✓ |

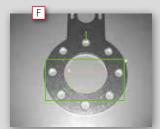
¹ not with color hardware V10C/V20C

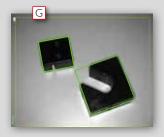












Guide to user interface

- A Select calibration plate: choice of four different sizes.
- B Start calibration: VISOR® is calibrated in just one click.
- C Fiducials: image coordinates mapped to robot coordinates at four points.
- Calibration method point pair list: calibration with point pair list (robot) for automatic calibration on object.
- **Gripping space check:** a freely accessible object is always output if available.
- Result offset: define the result point and therefore the position that the robot moves to on the component.
- Blob detector: localise components regardless of their shape and size. No need to teach a reference.

VISOR® Code Reader

Reads whatever is printed, dot-peened and lasered.



The VISOR® Code Reader from SensoPart easily reads barcodes of numerous types as well as printed and directly marked data matrix codes according to the ECC200 standard, regardless of the carrier materials (metal, plastic, paper, glass). The sensor even easily deciphers skewed or distorted codes, or those on to convex, reflective or transparent surfaces.

Built-in early warning system: the VISOR® Code Reader evaluates the quality of your printed and directly marked data matrix codes on the basis of standardised quality parameters according to ISO and AIM standards.

The VISOR® Code Reader Standard offers suitable tools for easily readable barcodes and data matrix codes (e.g. printed). The Advanced or Professional versions provide high-performance reading algorithms for difficult codes (e.g. directly marked).

HIGHLIGHTS OF VISOR® CODE READER

- Reliably reads barcodes as well as printed and directly marked data matrix codes, and even several codes simultaneously and mixed 1D/2D codes
- Supplementary object detection for characteristics other than codes
- Evaluation of quality parameters according to ISO/IEC 15415 and AIM DPM 2006
- Flexible definition of output data (header, trailer, net data)
- String comparison with message via the digital switching output
- Support of EtherNet/IP and DHCP, PROFINET
- · Comprehensive options for archiving images and data
- Reading of optical characters with OCR









Code on shiny metallic surface



Dot-peened code with external lighting



A lot of information in a small space: up to 2,334 ASCII symbols (7 bit) or 3,116 digits can be coded with an ECC-200 data matrix code.

| | Product variants | Resolution | Field of view | Integrated lighting |
|--------------|------------------|-------------|---------------|----------------------------|
| 20-CR-S3-xxx | Standard | 1440 × 1080 | wide | White, red or infrared LED |
| 20-CR-S3-xxx | Standard | 1440 × 1080 | medium | White, red or infrared LED |
| 20-CR-S3-xxx | Standard | 1440 × 1080 | narrow | White, red or infrared LED |
| 20-CR-A3-xxx | Advanced | 1440 × 1080 | wide | White, red or infrared LED |
| 20-CR-A3-xxx | Advanced | 1440 × 1080 | medium | White, red or infrared LEI |
| 20-CR-A3-xxx | Advanced | 1440 × 1080 | narrow | White, red or infrared LEI |
| 20-CR-A3-C-2 | Advanced | 1440 × 1080 | C-mount | None |
| 20-CR-P3-xxx | Professional | 1440 × 1080 | wide | White, red or infrared LED |
| 20-CR-P3-xxx | Professional | 1440 × 1080 | medium | White, red or infrared LEI |
| 20-CR-P3-xxx | Professional | 1440 × 1080 | narrow | White, red or infrared LED |
| 20-CR-P3-C-2 | Professional | 1440 × 1080 | C-mount | None |
| 10-CR-S3-xxx | Standard | 800 × 600 | wide | White, red or infrared LEI |
| 0-CR-S3-xxx | Standard | 800 × 600 | medium | White, red or infrared LE |
| 0-CR-S3-xxx | Standard | 800 × 600 | narrow | White, red or infrared LE |
| 0-CR-A3-xxx | Advanced | 800 × 600 | wide | White, red or infrared LEI |
| 10-CR-A3-xxx | Advanced | 800 × 600 | medium | White, red or infrared LEI |
| 0-CR-A3-xxx | Advanced | 800 × 600 | narrow | White, red or infrared LED |
| 0-CR-A3-C-2 | Advanced | 800 × 600 | C-mount | None |
| 0-CR-P3-xxx | Professional | 800 × 600 | wide | White, red or infrared LED |
| O-CR-P3-xxx | Professional | 800 × 600 | medium | White, red or infrared LED |
|)-CR-P3-xxx | Professional | 800 × 600 | narrow | White, red or infrared LED |
| 0-CR-P3-C-2 | Professional | 800 × 600 | C-mount | None |

The VISOR® Code Reader

System description

With its integrated object detection, the VISOR® Code Reader is unique in its price segment. The compact sensor reads conventional 1D barcodes, 2D data matrix codes and now also optical characters (OCR). It also has four detectors for object detection (pattern comparison, brightness, grey level and contrast), with which other object features – for example, stamps or logos – can be evaluated in a single reading pass. Codes and object features are even reliably detected with deviations from the taught-in position – using position tracking (optionally activated).

A special image filter with expanded setting options guarantees excellent reading performance even under difficult reading conditions. The test results can largely be evaluated within the sensor itself – with the option of string comparison or regular printouts – so, in many cases it eliminates the connection requirement to PLC or PC. If, however, this proves necessary, it can be easily and flexibly connected using freely available PLC function blocks for Siemens S7, Codesys and Allen Bradley.

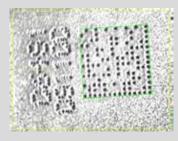
With integrated quality parameters complying with ISO and AIM standards, the VISOR® Code Reader also permits the informative evaluation of printed and direct marked 1D and 2D codes. Integrated red, infrared or white light variants provide maximum functional reliability through optimum code illumination.

In addition, the robust, compact and industry-oriented housings guarantee reliability even where space is restricted. Integrated 6 mm or 12 mm optics or C-mount devices also save effort and costs through their optimum adaptation to the most varied of code sizes and operating distances. The V20 variants also offer a resolution of 1.5 megapixels for particularly small codes or large search areas.

Product variants VISOR® Code Reader

| Product variants VISOR® C | ode Reade | er | |
|---|-------------------------------------|---|-----------------------|
| | VISOR® Code Reader | | |
| | Reading of barcodes, 2D codes, text | | |
| | Standard | Advanced | Professional |
| Resolution | | | |
| V10 V10C 800 × 600 | | Monochrome | |
| Number of images per second V10 V10 C | | 75 – | |
| V20 V20C 1440 × 1080 | - | | chrome |
| Number of images per second V20 V20 C Lighting | - - | nite, red¹, infrare | • |
| Multishot | *** | | |
| Target laser | - | , | / |
| Lenses | | | |
| V10 wide medium narrow c-mount | √ √ √ - | √ √ | √ √ |
| V20 wide medium narrow c-mount | - - - - | √ √ | √ √ |
| Interfaces | | | |
| Inputs outputs selectable | 2 2 4 | 2 3 | 2 6 |
| Encoder input | - | - - · ✓ | |
| Ethernet EtherNet/IP Profinet SensoWeb | | √ √ √ √ | |
| Service port | - | ✓ | |
| Job/Detectors | | | |
| Number of jobs (max.) | 8 | 255 | |
| Number of detectors per job (max.) | 2 | 255 | |
| Calibration | | | |
| Calibration (scaling, perspective) | - | | |
| Robot calibration Preprocessing | | _ | |
| Preprocessing filter | _ | _ | √ |
| Multiple image capture/Shutter variation | | _ | · · |
| Free-form search area | _ | _ | √ |
| Position tracking | | | |
| Contour comparison (translation, rotation | _ | - | √ |
| 360°) | | | |
| Pattern matching (translation, rotation 360°) | - ✓ | | • |
| Edge detection (translation, rotation) | - ✓ | | ~ |
| Object detection | | | |
| Contour comparison (translation, rotation 360°) | - | | |
| Multiple contour detection | - - ✓ | | |
| Pattern matching (translation, rotation 360°) | - · | | |
| Grey level Contrast Brightness Calliper | | | |
| BLOB | - | | |
| Identification | | | |
| Datacode | ✓ - | | |
| Datacode advanced | - ✓ | | |
| Barcode | ✓ – | | |
| Barcode advanced | - | 3 | / |
| Clear text (OCR) | | | |
| Robotics functions | | | |
| Result offset Checking space around gripper | | _ | |
| Checking space around gripper Color detectors ² | | | |
| Color field | | _ | |
| Color value | | _ | |
| Color list | | - | |
| Color distance Binarisation | | - | |
| | | | |





Dot-peened code on rough substrate

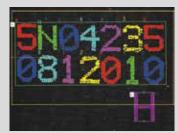
Code is made legible by powerful real

Code is made legible by powerful reading algorithm. Presence of the nailed imprint in plain text can be checked using object detection.



Low-contrast code

Code is made legible through high tolerance – also towards weakly contrasting



Optical character reading

Dot matrix printing can also be read with OCR



Code with small "quiet zone"

Even codes with a small quiet zone or damaged finder pattern can be read.



Code reading on solar cells

Even extremely small codes (e.g. on silicon solar cells) or highly reflective codes (e.g. on thin-layer solar cells) can be read.



Printed codes on pharmaceutical packaging

ECC200 or bar codes (e.g. EAN 13) can be searched for simultaneously. In addition to code reading, the presence of optical characters can also be checked using object detection.

Special features of the VISOR® Code Reader

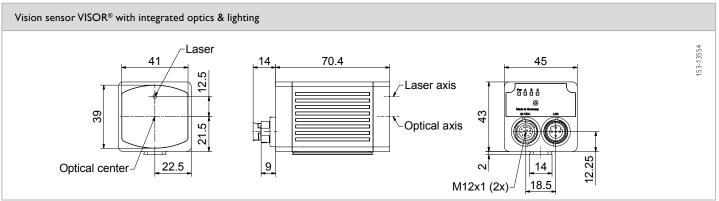
- Can be used for all common 2D codes (e.g. ECC 200 data matrix) and common 1D bar codes
- Optimum cost-effectiveness through combination of two functions in one device: code reading and object detection
- High operating dependability through reliable detection of even poorly readable codes under difficult ambient conditions
- Flexible and simple connection to PC and PLC environments due to comprehensive possibilities for archiving pictures and read results, as well as freely available PLC function blocks for Siemens S7, Codesys and Allen Bradley
- Very high flexibility, e.g. also due to reading several similar or different codes in one reading pass
- Reading of optical characters with OCR based on neural networks, particularly suitable for point printing

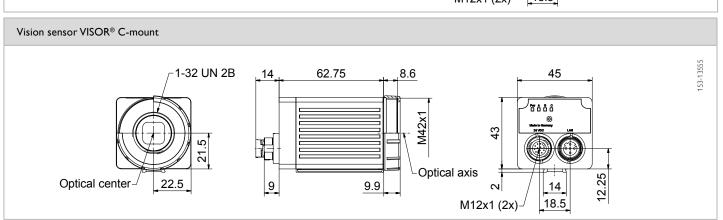
Technical data

| Optical data | | |
|---------------------------------|--|--|
| Number of pixels, chip size | VISOR®-V10: 800 (H) × 600 (V) VISOR®-V20: 1440 (H) × 1080 (V) | |
| Technology | CMOS (mono / color) | |
| Integrated measuring lighting | 8 LEDs (except C-mount) | |
| Integrated measurement distance | wide, medium, narrow, motorised focus | |
| | | |

| Electrical data | | Mechanical data | |
|-----------------------------------|---|--------------------------------|---|
| Operating voltage +U _B | 18 30 V DC ¹ | Dimensions | $71 \times 45 \times 45$ mm (without connector) |
| Power consumption (without I/O) | ≤ 300 mA | Enclosure rating | IP 67 |
| Protection circuits | Reverse-polarity protection, U _B / short-circuit protection of all outputs | Material housing | Aluminium, plastic, die-cast, RoHS compliant |
| Rise-time delay | Approx. 13 s after Power on | Material, front screen | Plastic |
| Outputs | PNP / NPN (switchable) | Ambient temperature: operating | 0 +50° C² |
| Max. output current (per output) | 50 mA, 100 mA (pin 12) | Ambient temperature: Storage | -20 +60° C² |
| Inputs | PNP/NPN High > U _R -1 V, Low < 3 V | Weight | Approx. 200 g |
| Input resistance | > 20 kΩ | Plug Connections | Supply and I/O M12, 12-pin, Ethernet |
| Encoder input | 40 kHz | | M12, 4-pin |
| Interfaces | Ethernet (LAN), RS422, RS232, EtherNet/IP, PROFINET, SensoWeb | Vibration / shock resistance | EN 60947-5-2 |
| Inputs / Outputs | 2 inputs, 2 outputs, 6 selectable inputs/outputs | c(UL)us (E | |

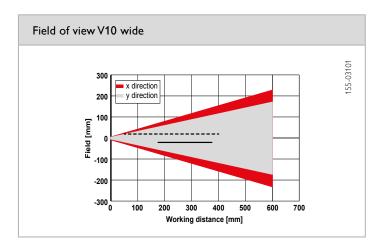
 $^{^{1}}$ Max, ripple < 5 V_{ss} 2 80 % air humidity, non-condensing 3 dependent on model

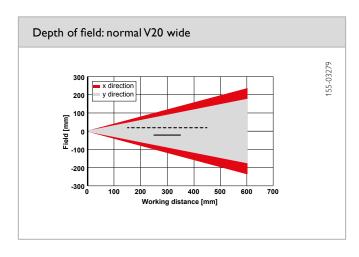


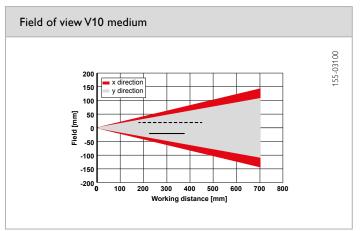


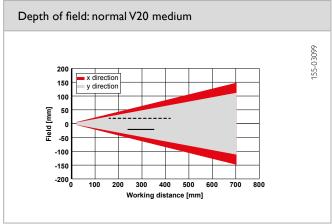
Fields of view and depths of field

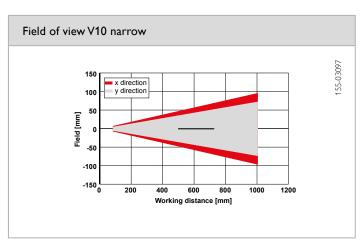


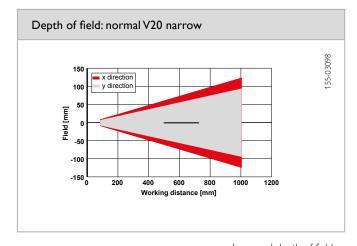












---- Increased depth of field
---- Normal depth of field

Brackets

| Brackets for V10, V20 (Cont.) | | | |
|-------------------------------|---|---|---|
| | | Part number / Article number | MG 3A / 543-11024 |
| | E 153-01-18 | Description | Mounting hinge with 3 axes and drilled hole for mounting rod Material: anodised aluminium |
| \$ 18 | 25 20 00 00 00 00 00 00 00 00 00 00 00 00 | Suitable for | V10 /V20 |
| • | M3 | Part number / Article number | MG 3A-MST12 / 543-11034 |
| | 153-1255 | Description | Mounting hinge with 3 axes for fixing at mounting rods 12 mm Material: anodised aluminium |
| 2811 | 10 do | Suitable for | V10 /V20 |
| 200 | <u> </u> | Mounting hinge (MG 45) | 10 |
| | \mathbb{R}^{-1} | | 153-00435 |
| | | Mounting block, rod (MB 45) | 153- |
| | | Mounting angle (MA 45) | |
| <u></u> | | Mounting clamp, | |
| <u>— Ц</u> | | dovetail (MK 45) Mounting rod (MST 45-x) | |
| | | Mounting plate (MP 45) | |
| | 100 | Mounting rod (MST 45-x) | |
| | . A-A 10 | Part number / Article number | MP 45 / 543-11003 |
| | 153-00547 | Description | Mounting plate for mounting rod Material: anodised aluminium |
| | | Suitable for | MST 45-xx |
| | (4) 11 (4) (4) (4) (4) (4) (4) (4) (4) (4) (4) | | |
| \ [| | Part number / Article number | MST 45-20 / 543-11005 MST 45-30 / 543-11006 MST 45-40 / 543-11007 |
| | x = 200 MST 45-20 | Description | Mounting rod with M6 internal thread Material: stainless steel |
| | x = 300 MST 45-30 x = 400 MST 45-40 | Suitable for | MP 45, MB ST1, MG 45, MB 45, MZ 45, MG 3A, MG 3A-MST12 |



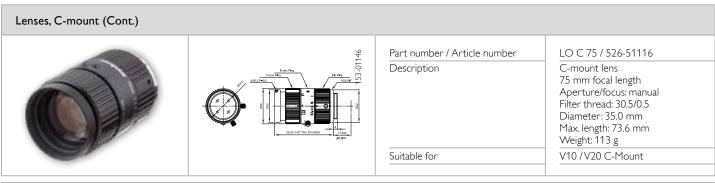


| Brackets for V10, V20 (Cont.) | | | |
|-------------------------------|--|---|--|
| | 20 00 00 00 00 00 00 00 00 00 00 00 00 0 | Part number / Article number Description Suitable for | MA 45 / 543-11001 Mounting angle Material: stainless steel V2A MK 45 MK 45 L MB 45 |
| | 60° 10 10 10 10 10 10 10 10 10 10 10 10 10 | Part number / Article number Description Suitable for | MA 45 L / 543-11013 Mounting angle, long Material: stainless steel V2A MK 45 MK 45 L MB 45 |
| | 10 10 10 10 10 20 | Part number / Article number Description Suitable for | MK 45 / 543-11000 Mounting clamp, dovetail Material: anodised aluminium Screw: steel V10 / V20 |
| | 14.5 14.5 12.8 19.4 37.4 | Part number / Article number Description Suitable for | MK 45 L / 543-11021 Mounting clamp, dovetail, long Material: anodised aluminium Screw: steel V10 / V20 |
| | 94500.E2T | Part number / Article number Description Suitable for | MZ 45 / 543-11004 Intermediate mounting piece for mounting rod Material: anodised aluminium MST 45-xx |

Lenses

| Lenses, C-mount | | | |
|-----------------|--|---|---|
| | 4 | Part number / Article number | LO C 8 / 526-51513 |
| | Tools fing MOSS Pring | Description Suitable for | C-mount lens 8 mm focal length Aperture/focus: manual Filter thread: 30.5/0.5 Diameter: 33.5 mm Max. length: 33.5 mm Weight: 70 g V10 /V20 C-Mount |
| | S S Holes Ring | Part number / Article number | LO C 12 / 526-51514 |
| | Note thing | Description Suitable for | C-mount lens 12 mm focal length Aperture/focus: manual Filter thread: 30.5/0.5 Diameter: 33.5 mm Max. length: 33.5 mm Weight: 65 g V10 /V20 C-Mount |
| | | D | 10.64/152/54545 |
| | Fotos Fing From Fing MOSS P-OS 10 10 10 10 10 10 10 10 10 10 10 10 10 1 | Part number / Article number Description Suitable for | LO C 16 / 526-51515 C-mount lens 16 mm focal length Aperture/focus: manual Filter thread: 30.5/0.5 Diameter: 33.5 mm Max. length: 33.5 mm Weight: 65 g V10 / V20 C-Mount |
| | | Part number / Article number | LO C 25 / 526-51516 |
| | Most First Mos | Description Suitable for | C-mount lens 25 mm focal length Aperture/focus: manual Filter thread: 30.5/0.5 Diameter: 33.5 mm Max. length: 44.9 mm Weight: 75 g V10 /V20 C-Mount |
| | 54 | Part number / Article number | LO C 35 / 526-51525 |
| | 1000 Blad 1000 Shall 1000 Sh | Description Suitable for | C-mount lens 35 mm focal length Aperture/focus: manual Filter thread: 30.5/0.5 Diameter: 33.5 mm Max. length: 47.5 mm Weight: 87 g V10 / V20 C-Mount |
| | φ. | Part number / Article number | LO C 50 / 526-51113 |
| | Form fing Form fing 100 100 100 100 100 100 100 100 100 10 | Description | C-mount lens 50 mm focal length Aperture/focus: manual Filter thread: 30.5/0.5 Diameter: 33.5 mm Max. length: 47.2 mm Weight: 90 g |
| | | Suitable for | V10 /V20 C-Mount |
| | | l . | |





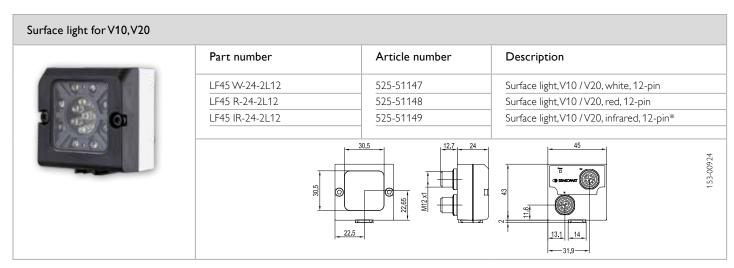
| Accessories, lenses | | | |
|---------------------|--|--|--|
| | Part number LR 5 ETS | Article number 543-11011 527-51143 | Description Intermediate ring 5 mm Intermediate ring set: 1 × 0,5 mm 1 × 10 mm 2 × 1 mm 1 × 20 mm 1 × 5 mm 1 × 40 mm |
| | Part number LOF-BP-R635- 30,5×0,5 LOF-LP-IR850- 30,5×0,5 LOF-PF-30,5 × 0,5 | Article number 533-01015 533-01010 526-51531 | Description Red filter for C-mount lens, Bandpass 610 - 660 nm Infrared filter for C-mount lens, Transmission > 825 nm Polarisation filter for C-mount lens |



LPT 45 CML 5L / 527-51134

Protective casing and polarizer glasses

| Protective casing and polarizer glasses (Cont.) | | | |
|--|---------------|------------------------------|---|
| | | Part number / Article number | LPCVxx / 651-01001 |
| The same of the sa | 55.8 | Description | Removable protective casing for Vx0 with integrated lens/lighting |
| | 23.5 31.5 | Suitable for | V10 /V20 |
| | 44.6 | Part number / Article number | LPC Vxx S1-5 / 651-01002 |
| | 9 27 | Description | Replacement panels (glass) for LPC Vxx, set of 5 pieces Material: coated glass |
| | | Suitable for | LPC Vxx |
| | | | |
| | 314.6 ZSEL-ES | Part number / Article number | LPFVxx S1 / 651-01003 |
| | | Description | Polarising filter panel for LPC Vxx |
| | 42.6 | Suitable for | (100% coverage) Material: coated glass V10 / V20 |
| | | | V107 V20 |
| | 3.14.6 | Part number / Article number | LPFVxx S2 / 651-01004 |
| | 314.6 | Description | Polarising filter panel for LPC Vxx (50% coverage, reversible) Material: coated glass |
| | | Suitable for | V10 /V20 |
| | | Part number / Article number | LPFVxx S1-5 / 651-01005 |
| | | Description | Polarising filter panel for LPCVxx (100% coverage), set of 5 pieces Material: coated glass |
| | | Suitable for | LPC Vxx |
| | | | |
| | | Part number / Article number | Z-USB-VISOR® / 651-01000 |
| A Down | | Description | USB stick with VISOR® PC software |
| The state of | | Suitable for | V10 /V20 |
| | | | |



^{*} External IR illumination can only be combined with IRTypes or C-Mount sensors.

 $LED\ area\ lighting\ for\ incidental\ illumination\ in\ IP67\ housings.\ Can\ be\ cascaded\ to\ illuminate\ from\ several\ directions.$

No switching amplifier required.

Illumination



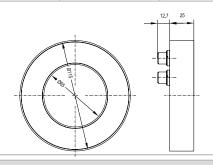
Angle bracket

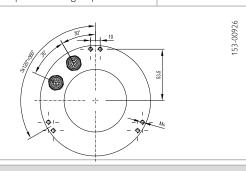
543-11015 543-11015 543-11015 543-11015 543-11015 543-11015

Ring light for V10, V20



| Part number | Article number | Description |
|--------------------|----------------|---|
| LFR 115 WD-24-2L12 | 525-51150 | Ring light,V10 /V20, white, diffuse, 12-pin |
| LFR 115 RD-24-2L12 | 525-51151 | Ring light,V10 /V20, red, diffuse, 12-pin |
| LFR 115 ID-24-2L12 | 525-51152 | Ring light, V10 / V20, infrared, diffuse, 12-pin* |
| LFR 115 WK-24-2L12 | 525-51153 | Ring light,V10 /V20, white, clear, 12-pin |
| LFR 115 RK-24-2L12 | 525-51154 | Ring light,V10 /V20, red, clear, 12-pin |
| LFR 115 IK-24-2L12 | 525-51155 | Ring light,V10 /V20, infrared, clear, 12-pin* |
| | | Does not require switching amplifier |





Spot illumination V10, V20

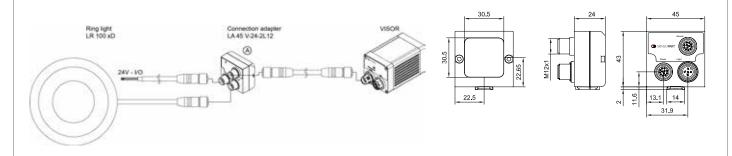


| Part number | Article number | Description |
|--|-------------------------------------|--|
| LS 55 × 46 WK-24-A13 2L12 LS 55 × 46 RK-24-A13 2L12 LS 55 × 46 iRK-24-A13 2L12 | 532-51101 532-51102 532-51103 | Ring light,V10/V20, white, diffuse, 12-pin Ring light,V10/V20, red, diffuse, 12-pin Ring light,V10/V20, infrared, diffuse, 12-pin* Does not require switching amplifier |

Connection adapter for illumination on V10, V20 V10, V20



| Part number | Article number | Description |
|----------------|----------------|--|
| LA45V-24-2L12 | 525-01001 | V10 / V20 connection adapter for LED illumination with 5-pin M12 plug |
| LA45VT-24-2L12 | 525-01002 | V10 / V20 connection adapter for LED illumination with 5-pin M12 plug, with trigger output |



^{*}External IR illumination is only possible for IR types or C-Mount sensors.

LED ring lighting for the incidental illumination of objects in IP67-tight housings. No switching amplifier is required and cascading is possible.

Cables

| Part number | Article number | Description |
|--|----------------|---|
| Power supply and I/O cables for V10,V20 (default) | | |
| C L12FG-S-2m-PUR | 902-51801 | Power supply and I/O cable, 2 m, M12, straight, 12-pin, shielded, suitable for drag chains |
| C L12FG-S-5m-PUR | 902-51796 | Power supply and I/O cable, 5 m, M12, straight, 12-pin, shielded, suitable for drag chains |
| C L12FG-S-10m-PUR | 902-51797 | Power supply and I/O cable, 10 m, M12, straight, 12-pin, shielded, suitable for drag chains |
| C L12FG-S-20m-PUR | 902-51805 | Power - I/O, cable, 20 m, M12, straight, 12-pin, shielded, suitable for drag chains |
| C L12FG-S-30m-PUR | 902-51845 | Power - I/O, cable, 30 m, M12, straight, 12-pin, shielded, suitable for drag chains |
| C L12FW-S-2m-PUR | 902-51798 | Power supply and I/O cable, 2 m, M12, 90°, 12-pin, shielded, suitable for drag chains |
| C L12FW-S-5m-PUR | 902-51799 | Power supply and I/O cable, 5 m, M12, 90°, 12-pin, shielded, suitable for drag chains |
| C L12FW-S-10m-PUR | 902-51800 | Power supply and I/O cable, 10 m, M12, 90°, 12-pin, shielded, suitable for drag chains |
| C L12FW-S-20m-PUR | 902-51821 | Power - I/O, cable, 20 m, M12, 90°, 12-pin, shielded, suitable for drag chains |
| C L12FW-S-30m-PUR | 902-51846 | Power - I/O, cable, 30 m, M12, 90°, 12-pin, shielded, suitable for drag chains |
| Power supply and I/O cables for | | |
| V10,V20 (3-pin) C L12/3FG-S-2m-PUR | 902-51833 | Power supply and I/O cable, 2 m, M12, straight, 3-pin (24V, GND, Trigger), shielded, suitable for drag chain |
| C L12/3FG-S-2m-PUR | 902-51833 | Power supply and I/O cable, 2 m, M12, straight, 3-pin (24V, GND, Trigger), shielded, suitable for drag chain Power supply and I/O cable, 5 m, M12, straight, 3-pin (24V, GND, Trigger), shielded, suitable for drag chain |
| C L12/3FG-S-10m-PUR | 902-51835 | |
| C L12/3FG-S-10III-FUR C L12/3FG-S-20m-PUR | 902-51839 | Power supply and I/O cable, 10 m, M12, straight, 3-pin (24V, GND, Trigger), shielded, suitable for drag cha |
| C L12/3FG-S-2011-FOR C L12/3FG-S-30m-PUR | 902-51847 | Power supply and I/O cable, 20 m, M12, straight, 3-pin (24V, GND, Trigger), shielded, suitable for drag chair |
| | 902-51836 | Power supply and I/O cable, 30 m, M12, straight, 3-pin (24V, GND, Trigger), shielded, suitable for drag cha |
| C L12/3FW-S-2m-PUR | 902-51837 | Power supply and I/O cable, 2 m, M12, 90°, 3-pin (24V, GND, Trigger), shielded, suitable for drag chair |
| C L12/3FW-S-5m-PUR | | Power supply and I/O cable, 5 m, M12, 90°, 3-pin (24V, GND, Trigger), shielded, suitable for drag chair |
| C L12/3FW-S-10m-PUR | 902-51838 | Power supply and I/O cable, 10 m, M12, 90°, 3-pin (24V, GND, Trigger), shielded, suitable for drag cha |
| C L12/3FW-S-20m-PUR | 902-51840 | Power supply and I/O cable, 20 m, M12, 90°, 3-pin (24V, GND, Trigger), shielded, suitable for drag cha |
| C L12/3FW-S-30m-PUR | 902-51848 | Power supply and I/O cable, 30 m, M12, 90°, 3-pin (24V, GND, Trigger), shielded, suitable for drag cha |
| Ethernet cables for V10/V20 | | |
| CI L4MG/RJ45G-GS-3m-PUR | 902-51754 | Ethernet cable, 3 m, M12, straight, 4-pin/RJ45, shielded, suitable for drag chains |
| CI L4MG/RJ45G-GS-5m-PUR | 902-51782 | Ethernet cable, 5 m, M12, straight, 4-pin/RJ45, shielded, suitable for drag chains |
| CI L4MG/RJ45G-GS-10m-PUR | 902-51784 | Ethernet cable, 10 m, M12, straight, 4-pin/RJ45, shielded, suitable for drag chains |
| CI L4MG/RJ45G-GS-20m-PUR | 902-51820 | Ethernet, cable, 20 m, M12, straight, 4-pin/RJ45 shielded, suitable for drag chains |
| CI L4MG/RJ45G-GS-30m-PUR | 902-51843 | Ethernet cable, 30 m, M12, straight, 4-pin/RJ45 shielded, suitable for drag chains |
| CI L4MW/RJ45G-GS-3m-PUR | 902-51786 | Ethernet cable, 3 m, M12, 90°, 4-pin/RJ45, shielded, suitable for drag chains |
| CI L4MW/RJ45G-GS-5m-PUR | 902-51788 | Ethernet cable, 5 m, M12, 90°, 4-pin/RJ45, shielded, suitable for drag chains |
| CI L4MW/RJ45G-GS-10m-PUR | 902-51790 | Ethernet cable, 10 m, M12, 90°, 4-pin/RJ45, shielded, suitable for drag chains |
| CI L4MW/RJ45G-GS-20m-PUR | 902-51822 | Ethernet cable, 20 m, M12, angled connector, 4-pin/RJ45 shielded, suitable for drag chains |
| CI L4MW/RJ45G-GS-30m-PUR | 902-51844 | Ethernet cable, 30 m, M12, angled connector, 4-pin/RJ45 shielded, suitable for drag chains |
| Illumination cables for V10/V20 | | |
| CB L12FS/L12FS-0,35m-GG-PUR | 902-51841 | Illumination cable $2 \times M12/12$ -pin, 0.35 m, straight, shielded, suitable for drag chains |
| CB L12FS/L12FS-0,5m-GG-PUR | 902-51806 | Illumination cable $2 \times M12/12$ -pin, 0.5 m, straight, shielded, suitable for drag chains |
| | 902-51807 | Illumination cable 2 × M12/12-pin, 2 m, straight, shielded, suitable for drag chains |
| CB L12FS/L12FS-2m-GG-PUR | | |
| CB L12FS/L12FS-2m-GG-PUR CB L12FS/L12FS-10m-GG-PUR | 902-51854 | Illumination cable $2 \times M12/12$ -pin, 10 m , straight, shielded, suitable for drag chains |
| | 902-51854 | Illumination cable $2 \times M12/12$ -pin, 10 m , straight, shielded, suitable for drag chains Illumination cable $2 \times M12/12$ -pin, 0.35 m , 90° , shielded, suitable for drag chains |
| CB L12FS/L12FS-10m-GG-PUR | | |

PV-AW10IoT10.4TX(-V)



Display and configuration device for SensoPart vision sensors





PRODUCT HIGHLIGHTS

- Display and configuration device for SensoPart vision sensors and systems
- Suitable for installation in switching cabinet doors and operating panels
- Completely preconfigured

| Functions | |
|---------------------|-----------------------|
| Resolution | 1024 × 768 |
| Aspect ratio | 4:3 |
| Technology | TFT |
| Colors | 16.2 millions |
| Backlight | LED |
| Backlight life time | 30,000 h |
| Luminance 1) | 350 cd/m ² |
| Contrast ratio 1) | 1200 : 1 |
| Operating system | Windows® 10 IoT |

| Electrical data | | Mechanical data | |
|-----------------------------------|----------------------------------|--------------------------------|-----------------------|
| Operating voltage +U _B | 24V DC ± 20 % | Dimensions | 266 × 213.2 × 52.4 mm |
| CPU | AMD® GX-415GA / Quad Core™ / 1.5 | Enclosure rating | IP 65 |
| | GHz 64 Bit / 2 MB Cache | Ambient temperature: operation | 0 +50 °C |
| USB | 2 x USB Host 3.0 | Ambient temperature: storage | -10 +70 °C |
| Ethernet | 2 x 1 Gbit Ethernet | Weight | 1700 g |
| Communication | 1 x RS232 | | |
| Video | 1 x DVI-I | | |
| Memory | 4 GB DDR3L | | |
| Storage | 64 GB MLC | | |
| BIOS | AMI BIOS, supports ACPI function | | |

¹ The values are refferring to the displays only

| Part number | Article number | Description |
|--------------------|----------------|--|
| PV-AW10IoT10.4TX | 533-01031 | Panel PC 10.4", Win10 IoT, XGA, Touch, front panel mount |
| PV-AW10IoT10.4TX-V | 533-01032 | Panel PC 10.4", Win10 IoT, XGA, VESA mount |

| Accessories | |
|-----------------------------------|----------------|
| Connection cable (Ethernet cable) | From Page A-34 |

Calibration accessories for SensoPart vision sensors

| | | | _ | |
|--------------|-------------------|---|----------|--|
| Part number | Article number | Description | Тур | |
| ZCP 50-13x15 | 533-11030 | 15×13 points, 50 mm × 37,9 mm | Standard | |
| ZCP 100-13×1 | 5 533-11031 | 15×13 points, 100 mm × 75,8 mm | Standard | |
| ZCP 200-13×1 | 5 533-11032 | 15×13 points, 200 mm × 151,7 mm | Standard | |
| ZCP 500-13×1 | 5 533-11033 | 15×13 points, 500 mm × 379,2 mm | Standard | |
| ZCP 50-13×15 | -X01 533-11037 | 15×13 points, crosshairs, 50 mm × 37,9 mm | X01 | |
| ZCP 50-13×15 | -X01 533-11038 | 15x13 points, crosshairs, 100 mm x 75,8 mm | X01 | |
| ZCP 100-13×1 | 5-X01 533-11039 | 15×13 points, crosshairs, 200 mm × 151,7 mm | X01 | |
| ZCP 200-13×1 | 5-X01 533-11040 | 15×13 points, crosshairs, 500 mm × 379,2 mm | X01 | |
| ZCP 500-13×1 | 5-X01 533-11035 | 15×13 points, fiducials, 100 mm × 75,8 mm | X02 | |
| ZCP 50-13×15 | -X03 533-11042 | 15×13 points, fitting holes, 50 mm × 37,9 mm | X03 | |
| ZCP 100-13×1 | 5-X03 533-11041 | 15×13 points, fitting holes, 100 mm × 75,8 mm | X03 | |
| ZCP 100-ECC | 200 533-11036 | Calibration plate for Code Reader ECC200 quality parameters | - | |

The calibration plates are used for calibrating the VISOR® vision sensor.

Scaling, tilt angle against perpendicular view to the measurement plane or by lens distortion are all corrected.

| a | 153-13531 | | a [mm] | b [mm] | c [mm] | d [mm] | e Ø [mm] | t | Recommended field of view [mm] |
|---|-----------|---------------|-----------|-----------|-----------|-----------|-------------|---|--------------------------------|
| 0 | | ZCP 50-13×15 | 54 | 47 | | | | 2 | 22 - 50 |
| | | ZCP 100-13×15 | 104 | 85 | | | | 2 | 30 - 100 |
| | | ZCP 200-13×15 | 204 | 161 | | | | 4 | 60 - 200 |
| | | ZCP 500-13×15 | 504 | 389 | | | | 4 | 150 - 500 |
| | | | | | | | | | |

Supports calibration method "Calibration plate (Measurement)". Reference marks: none.

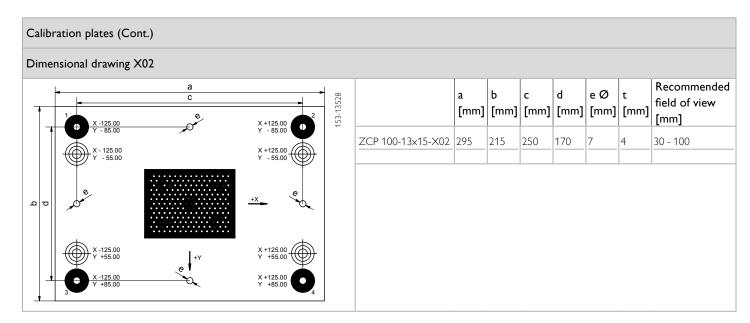
| Din | Dimensional drawing X01 | | | | | | | | | |
|-----|---|--|------------------|------------------|-----------|-----------|-------------|-------------|--------------------------------------|--|
| 1 | a 2 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 | | a [mm] | b [mm] | c [mm] | d [mm] | e Ø [mm] | t [mm] | Recommended field of view [mm] | |
| р | | ZCP 50-13×15-X01 ZCP 100-13×15-X01 ZCP 200-13×15-X01 | 98 180 340 | 54 100 176 | | | | 2 2 4 | 22 - 50 30 - 100 60 - 200 | |
| | | ZCP 500-13×15-X01 | 820 | 403 | | | | 4 | 150 - 500 | |

Supports calibration method "Calibration plate (Robotics)".

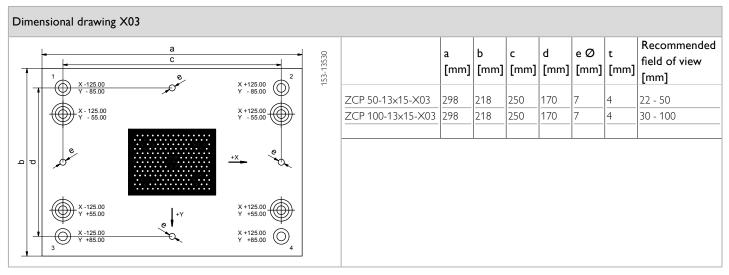
With the reference marks, a reference to the absolute coordinate system is established.

Reference marks: crosshairs.

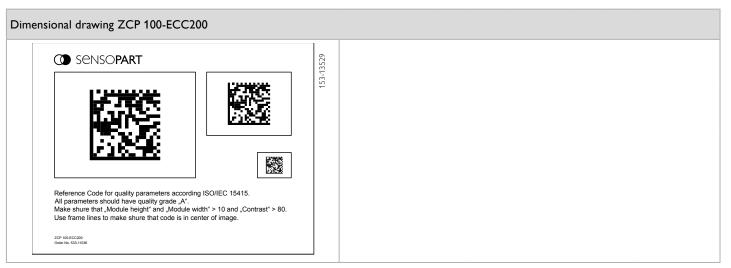




For establishing an absolute reference, reflex marks are available. The transformation is calculated in the robot. Reference marks: fiducials, crosshairs.



See version X02. Reference marks: fitting holes, crosshairs.



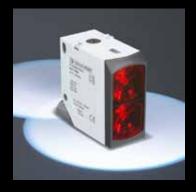
Calibration plate for ECC200 Codes, sample code in quality grade "A" according ISO/IEC 15415.

We look ahead

Yesterday, today and in the future













"We gauge ourselves not by what is possible today, but by our vision of what can be achieved" – this has been our motto since the foundation of SensoPart in 1994. Our goal is to always be a step ahead and to be able to offer our customers the most innovative sensor for industrial automation.

True to this motto, we offer easy-to-integrate VISOR® vision sensors and compact laser sensors with outstanding background suppression made in Germany.

We still also have plenty of ideas for the future - watch this space.

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Color detection

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Lighting

Lenses



SCAN ME



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